# Prediction Workshop

Data Analysis

Presented by:

Jennifer Heeg

Aeroelasticity Branch, NASA Langley Research Center On behalf of the AePW Organizing Committee

#### **Contents**

- Status of data analyses
- Comparison results: Describe the data analysis processes for the experimental data sets
  - Steady data
  - Frequency response functions
- Displacement amplitude for input to analyses

### **Comparison Data Matrix**

		Marie Control of the			
	REQUIRED CALCULA			ATIONS	
CONFIGURATION	GRID CONVERGENCE STUDIES	TIME CONVERGENCE STUDIES	STEADY CALCULATIONS	DYNAMIC CALCULATIONS	
Steady-Rigid Cases (RSW, BSCW)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	<ul> <li>Mean C<sub>p</sub> vs. x/c</li> <li>Means of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub></li> </ul>	n/a	
Steady-Aeroelastic Cases (HIRENASD)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	<ul> <li>Mean C<sub>p</sub> vs. x/c</li> <li>Means of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub></li> <li>Vertical displacement vs. chord</li> <li>Twist angle vs. span</li> </ul>	n/a	
Forced Oscillation Cases (all configurations)	<ul> <li>Magnitude and Phase of CL, CD, CM vs. N<sup>-2/3</sup> at excitation frequency</li> </ul>	<ul> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> vs. Δt at excitation frequency</li> </ul>	n/a	<ul> <li>Magnitude and Phase of C<sub>p</sub> vs. x/c at span stations corresponding to transducer locations</li> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> at excitation frequency</li> <li>Time histories of C<sub>p</sub>'s at a selected span station for two upper- and two lower-surface transducer locations</li> </ul>	

#### Comparison Data Matrix: Experimental Data Analysis

Completed In progress Stalled

		REQUIRED CALCULATIONS				
	CONFIGURATION	GRID CONVERGENCE STUDIES	TIME CONVERGENCE STUDIES	STEADY CALCULATIONS	DYNAMIC CALCULATIONS	
イボー大き	Steady-Rigid Cases (RSW, BSCW)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	<ul> <li>Mean C<sub>D</sub> vs. x/c</li> <li>Means of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub></li> </ul>	n/a	
	Steady-Aeroelastic Cases (HIRENASD)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	<ul> <li>Mean C<sub>n</sub> vs. x/c</li> <li>Means of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub></li> <li>Vertical displacement vs. chord</li> <li>Twist angle vs. span</li> </ul>	n/a	
	Forced Oscillation Cases (all configurations)	<ul> <li>Magnitude and Phase of CL, CD, CM (vs. N<sup>-2/3</sup> at excitation frequency)</li> </ul>	<ul> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> (vs. ∆t at excitation frequency)</li> </ul>	n/a	<ul> <li>Magnitude and Phase of C<sub>p</sub> vs. x/c at span stations corresponding to transducer locations</li> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> at excitation frequency</li> <li>Time histories of C<sub>p</sub>'s at a selected span station for two upper- and two lower-surface transducer locations</li> </ul>	

In-progress Experimental Data Analysis:

**Balance loads** 

Balance data exists for calculating comparison data only for HIRENASD

**Status:** Not complete

**Issues:** Axis definitions, orientation,

norn	nalizations, tra	nsformations,	V	
Steady-Rigid Cases (RSW, BSCW)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	<ul> <li>Mean C<sub>p</sub> vs. x</li> <li>Means of C<sub>L</sub>, 0</li> </ul>	Re=14.0 Mio. Re=23.5 Mio. Re=50.0 Mio.
Steady-Aeroelastic Cases (HIRENASD)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	<ul> <li>Mean C<sub>D</sub> vs. x/c</li> <li>Means of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub></li> <li>Vertical displacement vs. chord</li> <li>Twist angle vs. span</li> </ul>	n/a
Forced Oscillation Cases (all configurations)	<ul> <li>Magnitude and Phase of CL, CD, CM (vs. N<sup>-2/3</sup> at excitation frequency)</li> </ul>	<ul> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> (vs. Δt at excitation frequency)</li> </ul>	n/a	<ul> <li>Magnitude and Phase of C<sub>p</sub> vs. x/c at span stations corresponding to transducer locations</li> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> at excitation frequency</li> <li>Time histories of C<sub>p</sub>'s at a selected span station for two upper- and two lower-surface transducer locations</li> </ul>

From Aachen University published results

Ma = 0.80,

q/E=0.48e-6

0.5

0.4

0.3 -

### Steady (Static) Experimental Data

	た。大学など大学へにた	THE LIFE THE STATE OF THE STATE	I No.		
5 77.7		REQUIRED CALCULATIONS			
	CONFIGURATION	GRID CONVERGENCE STUDIES	TIME CONVERGENCE STUDIES	STEADY CALCULATIONS	DYNAMIC CALCULATIONS
	Steady-Rigid Cases (RSW, BSCW)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	• Mean C <sub>p</sub> vs. x/c	n/a
	Steady-Aeroelastic Cases (HIRENASD)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	<ul> <li>Mean C<sub>p</sub> vs. x/c</li> <li>Integrity of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub></li> <li>Vertical displacement vs. chord</li> <li>Twist angle vs. span</li> </ul>	n/a
	Forced Oscillation Cases (all configurations)	<ul> <li>Magnitude and Phase of CL, CD, CM vs. N<sup>-2/3</sup> at excitation frequency</li> </ul>	<ul> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> vs. Δt at excitation frequency</li> </ul>	n/a	<ul> <li>Magnitude and Phase of C<sub>p</sub> vs. x/c at span stations corresponding to transducer locations</li> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> at excitation frequency</li> <li>Time histories of C<sub>p</sub>'s at a selected span station for two upper- and two lower-surface transducer locations</li> </ul>

#### Steady (or Static) Pressure Coefficients

#### RSW:

- Historical tabulated values, obtained from archival publications, available through RTO
- Based on steady state measurements; mean values

#### BSCW

- Calculated from time history data
- Steady point: Mixed mean and mode values
- Oscillatory points: Mean values of unsteady time histories

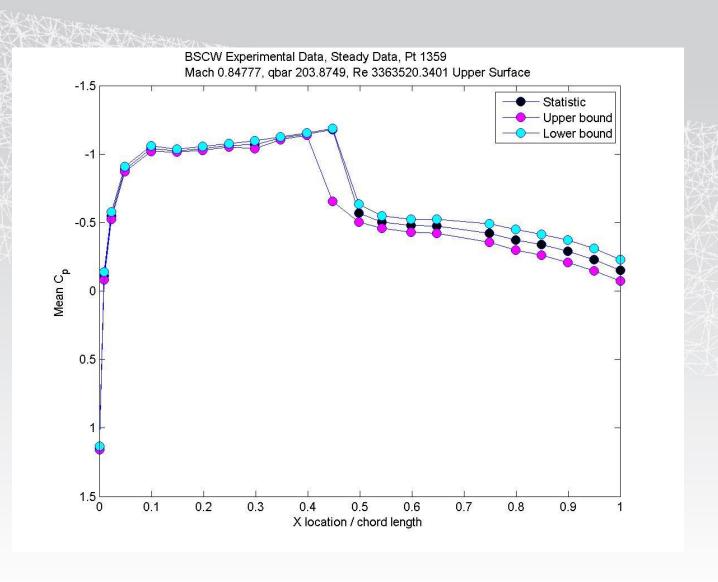
#### HIRENASD

- Angle of attack polar data: pressures did not stabilize
- Non-excitation portions of oscillatory time histories used;
   mean values

#### **BSCW Steady Pressure Distribution**

- Non-oscillatory data point:
  - For almost all sensors:
    - Mean value calculated
    - +/- 3 standard deviations used as upper and lower bounds
  - For shock-traversed sensor:
    - Mode value calculated
    - 1% and 99% values used as upper and lower bounds
- Oscillatory data point:
  - Mean values calculated

#### BSCW steady data

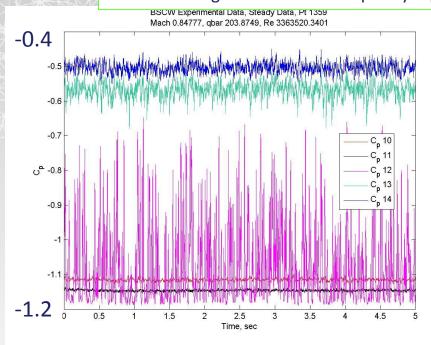


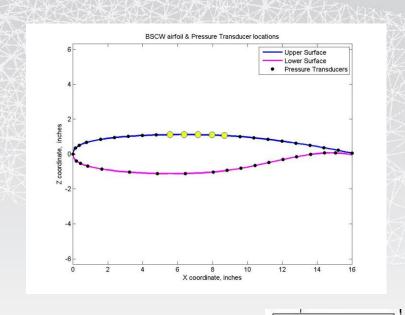
## BSCW Static Data: Steady Cp estimates from non-oscillated data

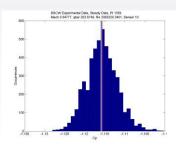
Data is assumed to be Gaussian when the mean is calculated. For BSCW:

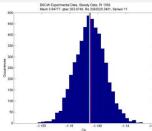
Most pressures are approximately Gaussian

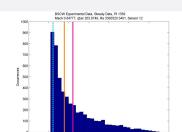
Data in the region of the shock is poorly represented in this way

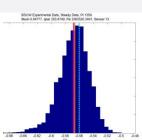


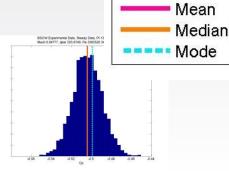










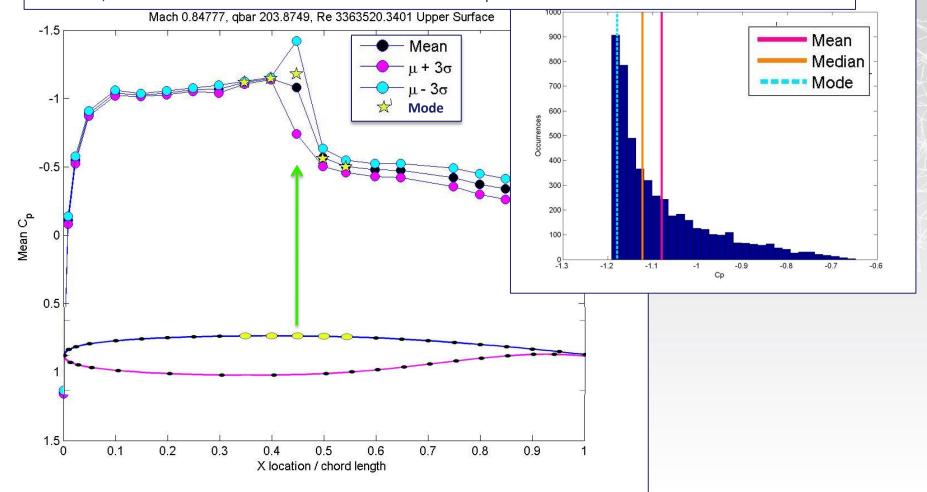


#### BSCW Static Data: Steady Cp estimates from non-oscillated data

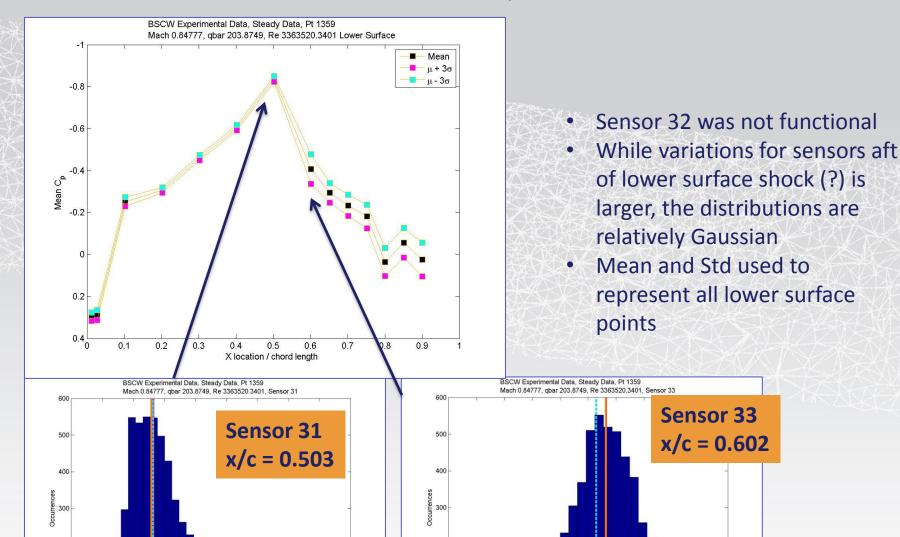
Using the mean value to represent the steady distribution:

Shock strength underestimated

- → Value at transducer 12: Mean value is 8% too low if mode is considered as the proper estimated value
- → The lower bound shown, turquoise circle, represents a value that is never achieved (overestimate of bound)
- $\rightarrow$  The upper bound, magenta circle, does not capture 99% of the data which is implied by the  $3\sigma$  calculations (underestimate of bound)
- → Mode, 99% and 1% values used instead of mean and std for this point



#### **BSCW Static Point, Lower Surface**



200

100

-0.42

-0.4

-0.46

-0.44

200

100

-0.83

-0.825

-0.82

-0.815

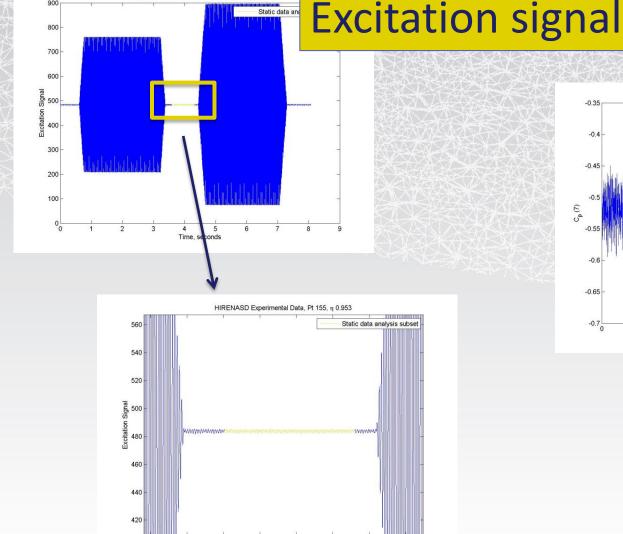
#### HIRENASD Static Data

- Mode not used as replacement for HIRENASD data
  - It's more difficult
    - More sensors to evaluate
    - More cases to evaluate
  - Gaussian assumption not as bad as for BSCW shock
  - Multiple sensors display "moderately" non-Gaussian characteristics
  - Need method to quantify "good enough" in terms of Gaussian assumption
  - OR ... Decide to replace mean and standard deviation with other statistics

#### HIRENASD Steady Data Selection

- Each HIRENASD oscillatory point contains 2 regions of oscillation: low excitation and high excitation
- These excitations are separated by several seconds

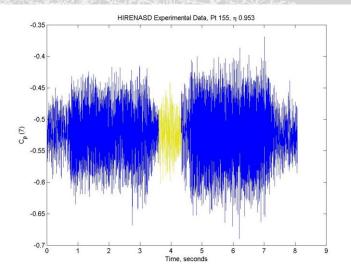
### HIRENASD data subset for static analysis: time histories



4.2

3.6

HIRENASD Experimental Data, Pt 155, η 0.953



Example pressure subset

### Frequency Response Functions

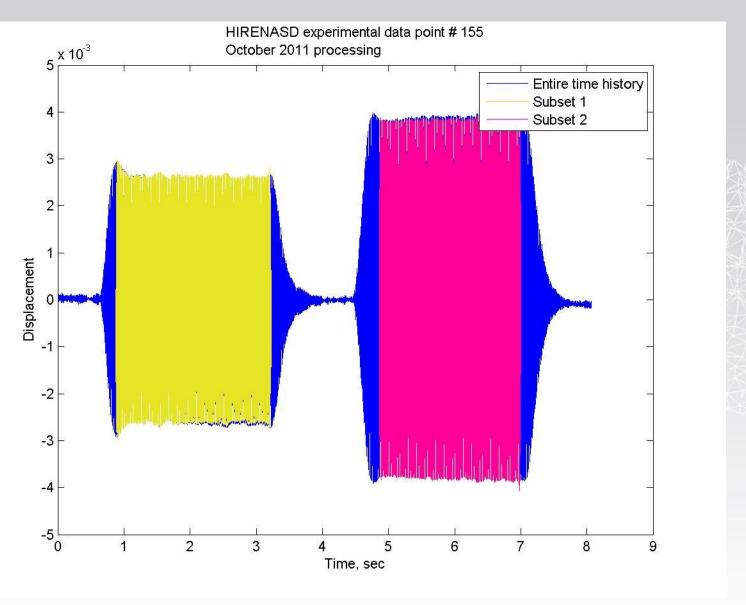
		A TO THE RESIDENCE OF A STATE OF	INC.		
		REQUIRED CALCULATIONS			
	CONFIGURATION	GRID CONVERGENCE STUDIES	TIME CONVERGENCE STUDIES	STEADY CALCULATIONS	DYNAMIC CALCULATIONS
マボナ人へ	Steady-Rigid Cases (RSW, BSCW)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	/ n/a	<ul> <li>Mean C<sub>p</sub> vs. x/c √</li> <li>Means of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> √</li> </ul>	n/a
	Steady-Aeroelastic Cases (HIRENASD)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	<ul> <li>Mean C<sub>p</sub> vs. x/c</li> <li>Means of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> √</li> <li>Vertical displacement vs. chord</li> <li>Twist angle vs. span √</li> </ul>	n/a
	Forced Oscillation	<ul> <li>Magnitude and Name of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> vs. N<sup>-2/3</sup> at</li> </ul>	Magnitude and ✓ Phase of C <sub>L</sub> , C <sub>D</sub> , C vs At at	/ n/a	<ul> <li>Magnitude and Phase of C<sub>p</sub> vs. x/c at span stations corresponding to transducer locations</li> </ul>
	(all configurations)	excitation frequency	$C_M$ vs. $\Delta t$ at excitation frequency	II/a	<ul> <li>excitation frequency</li> <li>Time histories of C<sub>p</sub>'s at a selected span station for two upper- and two lower-surface transducer locations</li> </ul>

HIRENASD Exp Data, Pt 159: FRFs of Cp due to displacement, frequency = 78.8294 Hz 2 Fourier Block Size 12299 Section I 75% overlap Rectangular window Detrended Section 2 Magnitude 1.5 0.5 Section 3 Section 4 Section 5 Section 6 Section 7 Oscillation of 2nd Bending Mode Yellow Filledi Black Filledi upper surface, Exp 159 lower surface, Exp 159 Magnitude 1.5 Magnitude Magnitude Magnitude 8 Magnitude 6 Magnitude 0, 0 0.2 0.4 0.8 0.2 0.4 0.6 0.8 0.6 0 x/c x/c

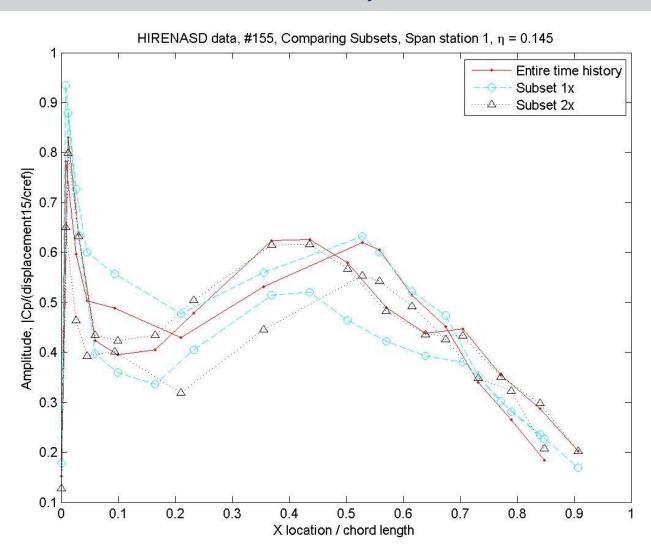
#### Considerations in computing FRFs

- Subset selection
- Displacement by integration of acceleration
- Fourier analysis block size determination

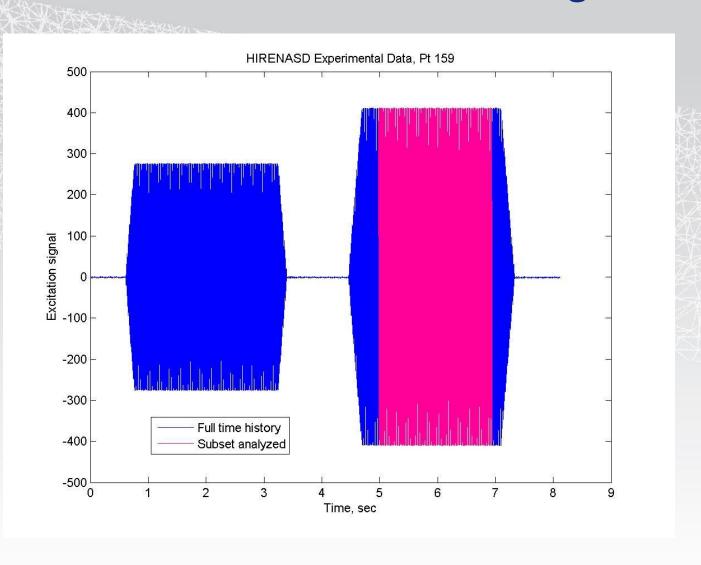
### HIRENASD oscillatory data



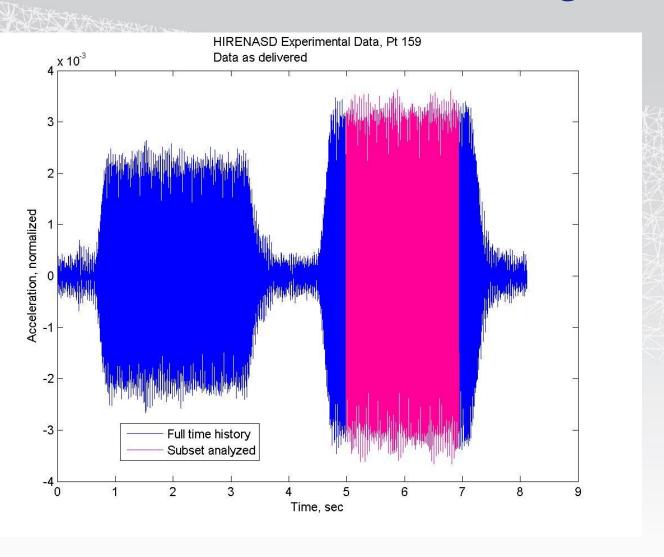
### HIRENASD FRF, subset effects



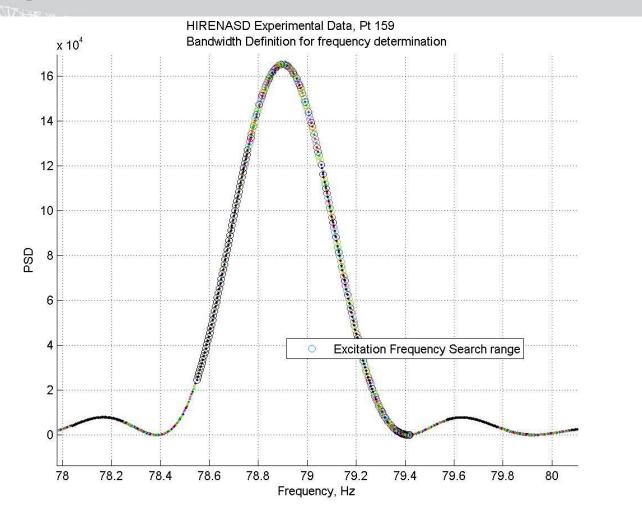
# HIRENASD data subset used for unsteady data reduction- Excitation signal



# HIRENASD data subset used for unsteady data reduction- Acceleration signal



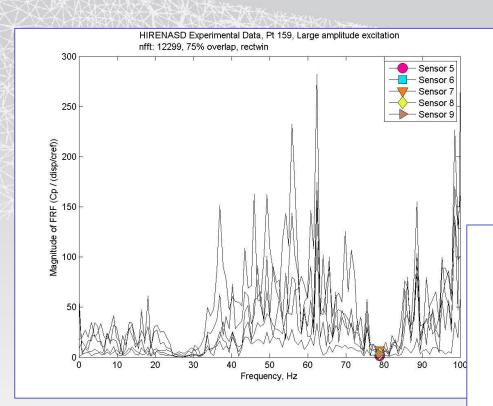
### Fourier analysis: analysis time length varied by 1 sample increments to determine block size

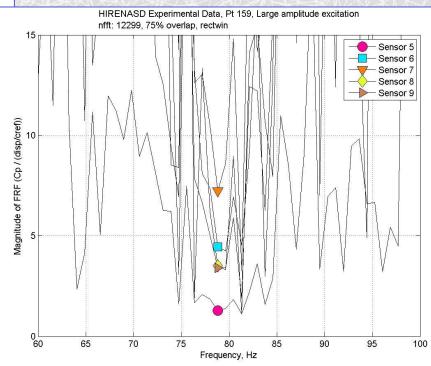


Power spectral density function of excitation signal:

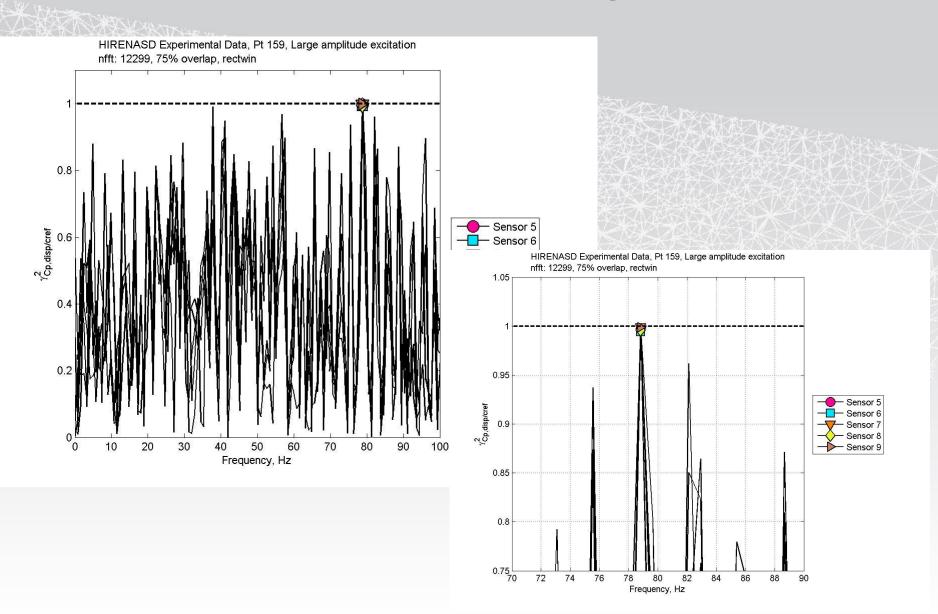
Analysis block size determined by minimum standard deviation among ensembles

## Frequency response functions for several transducers

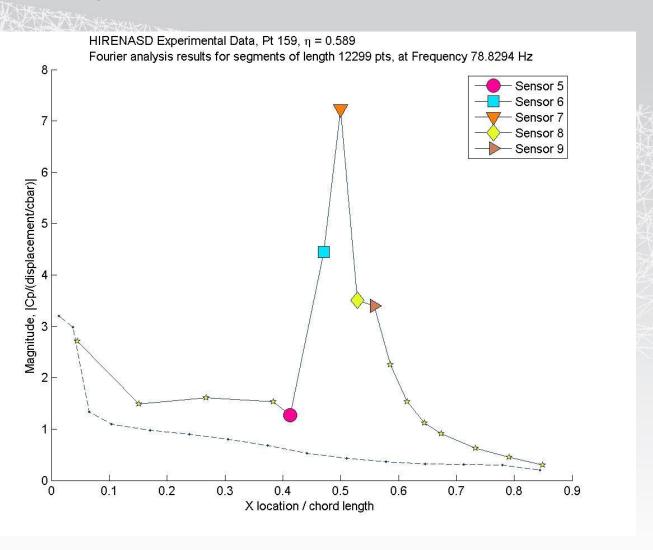




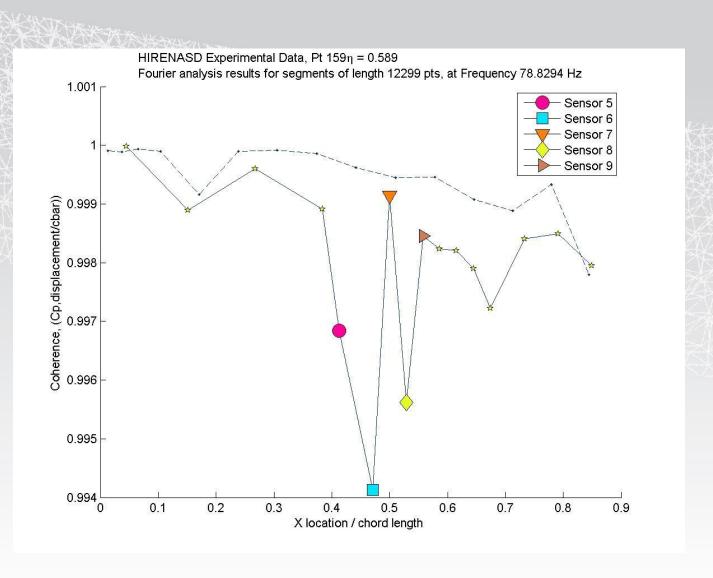
### Coherence for corresponding transducers



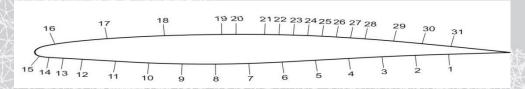
# Frequency response function at excitation frequency: all sensors at 1 span station

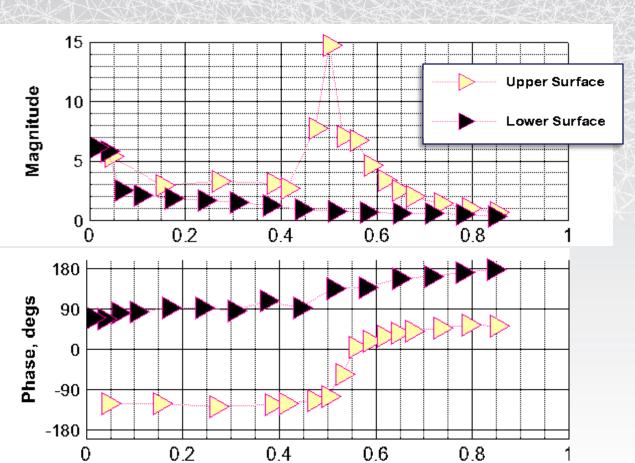


### Corresponding coherence



# Example of dynamic comparison data: HIRENASD Frequency Responses at 2<sup>nd</sup> Bending Mode Frequency (78.9 Hz)

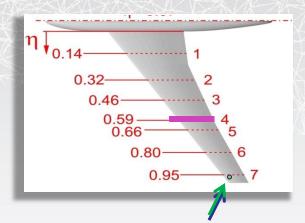




x/c

Cp(x)/displacement

Pressure coefficients at span station 4 due to displacement at location (15,1)

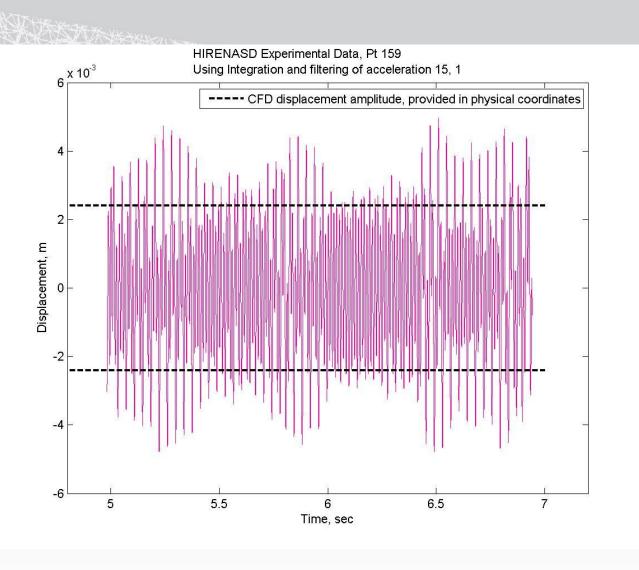


Reference quantity: Displacement at location (15,1) HIRENASD Exp Data, Pt 159: FRFs of Cp due to displacement, frequency = 78.8294 Hz 2 Fourier Block Size 12299 Section I 75% overlap Rectangular window Detrended Section 2 Magnitude 1.5 0.5 Section 3 Section 4 Section 5 Section 6 Section 7 Oscillation of 2nd Bending Mode Yellow Filledi Black Filledi upper surface, Exp 159 lower surface, Exp 159 Magnitude 1.5 Magnitude Magnitude Magnitude 8 Magnitude 6 Magnitude 0, 0 0.2 0.4 0.8 0.2 0.4 0.6 0.8 0.6 0 x/c x/c

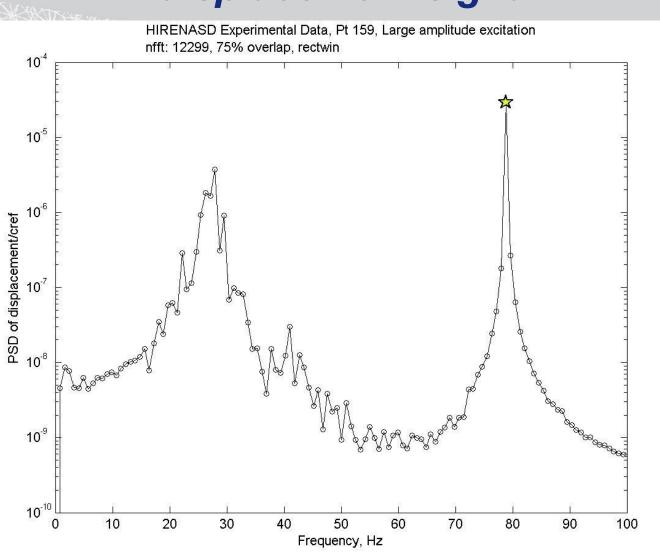
#### CFD displacement amplitude calculation

Fourier analysis of integrated displacement

### HIRENASD data, displacement signal



# HIRENASD data, Fourier analysis of displacement signal



#### HIRENASD Response Amplitudes

#### Updated information:

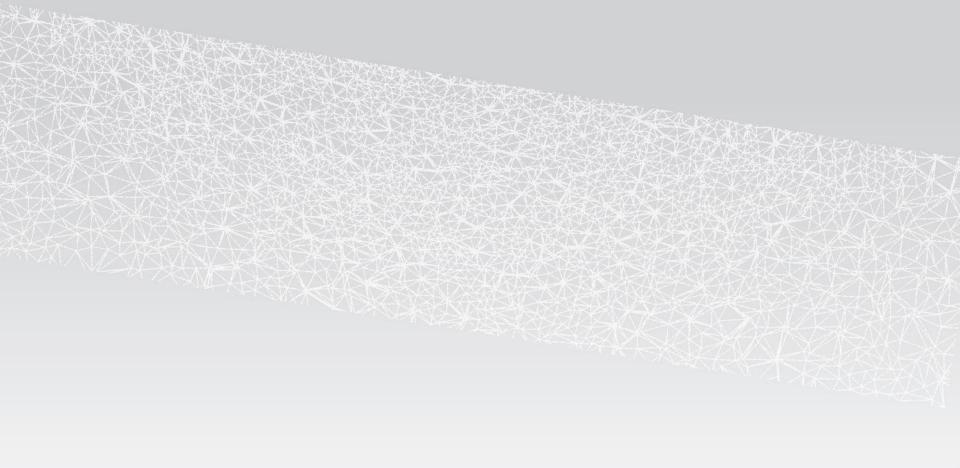
 Amplitude of excitations for 2<sup>nd</sup> bending modes for each of the 3 unsteady cases, extracted from the experimental data:

Exp Test Pt	159	271	155
Mach #	0.8	0.8	0.7
Re <sub>c</sub>	7M	23.5M	7M
Amplitude (mm)	2.4	0.90	2.0
Frequency (Hz)	78.9	80.4	79.3

For those analysts using strictly forced oscillations (similar methodology to RSW and BSCW), it is recommended that they use the frequencies extracted from the experimental data at the test conditions, as given in the table above. It is recommended that they oscillate the model in the 2<sup>nd</sup> bending mode shape as given by the finite element model.

For those analysts who are performing a coupled aeroelastic analysis, proximity of the oscillatory frequency to the modal frequency may be a dominant effect, and these frequencies are likely not exactly correct. The next slide contains a summary of the air-off natural frequencies of the 2<sup>nd</sup> bending mode. The first 2 columns show the experimental data; the last column shows the current finite element model frequency.

#### **Additional Information**



### **Comparison Data Matrix**

X KISHTATA X	ボイアメ		N. C.		
<u> </u>		REQUIRED CALCULATIONS			
CONFIGU	RATION	GRID CONVERGENCE STUDIES	TIME CONVERGENCE STUDIES	STEADY CALCULATIONS	DYNAMIC CALCULATIONS
Steady-Rig (RSW, B	gid Cases SCW)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	/ n/a	<ul> <li>Mean C<sub>p</sub> vs. x/c √</li> <li>Means of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> √</li> </ul>	n/a
Steady-Ae Case (HIREN	es	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	<ul> <li>Mean C<sub>p</sub> vs. x/c</li> <li>Means of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> ✓</li> <li>Vertical displacement vs. chord</li> <li>Twist angle vs. span ✓</li> </ul>	n/a
Forced Os Case (all configu	es	<ul> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> vs. N<sup>-2/3</sup> at excitation frequency</li> </ul>	Magnitude and v Phase of C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. ∆t at excitation frequency	n/a	<ul> <li>Magnitude and Phase of C<sub>p</sub> vs. x/c at span stations corresponding to transducer locations</li> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> at excitation frequency</li> <li>Time histories of C<sub>p</sub>'s at a selected span station for two upper- and two lower-surface transducer locations</li> </ul>

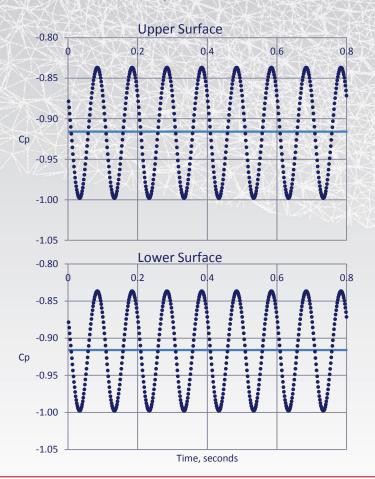
# RSW – BSCW – HIRENASD c<sub>D</sub> Time Histories One ch

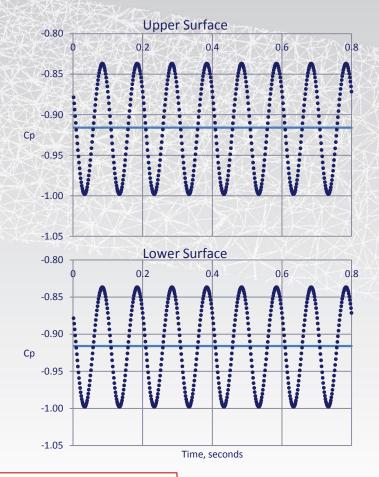
One chart per configuration

At chord locations where upper-surface  $c_p$  is peak as determined by -

- Experiment

- Computation





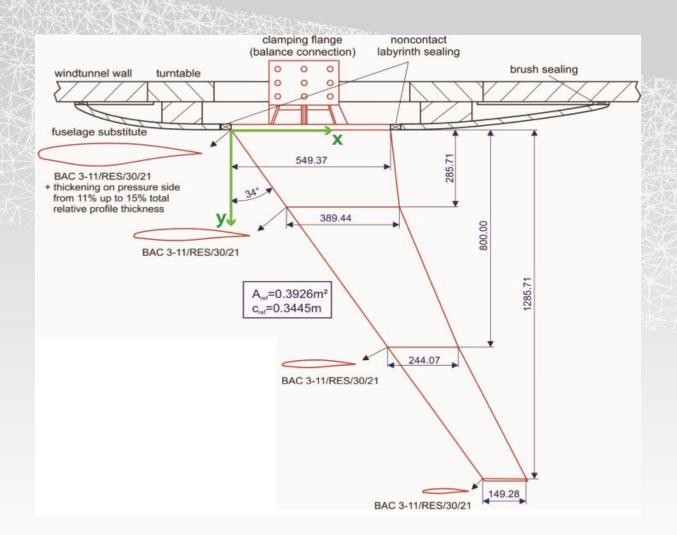
The purpose of this series of charts is to look for evidence of nonlinearities in the computational aeroelastic solutions.

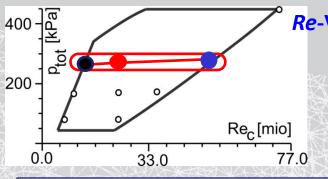
For each configuration, for two specified pairs of points within a specified span station, time histories of analytically-predicted C<sub>o</sub>'s are plotted:

1. The first pair is comprised of the upper- and lower-surface C<sub>p</sub>'s at the chordwise position where fourier analysis of the experimental data shows the experimental upper-surface C<sub>p</sub> to be at its peak;
2. The second pair is comprised of the upper- and lower-surface C<sub>n</sub> to be at its peak.

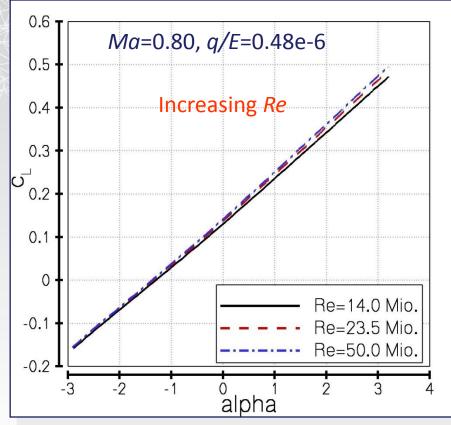
# **Comparison Data Matrix**

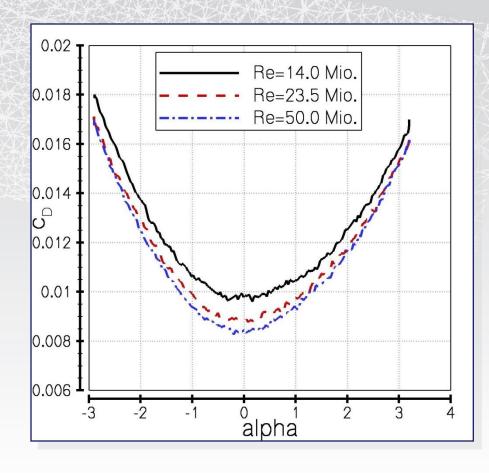
		REQUIRED CALCULATIONS			
	CONFIGURATION	GRID CONVERGENCE STUDIES	TIME CONVERGENCE STUDIES	STEADY CALCULATIONS	DYNAMIC CALCULATIONS
マネルと	Steady-Rigid Cases (RSW, BSCW)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	<ul> <li>Mean C<sub>p</sub> vs. x/c</li> <li>Means of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub></li> </ul>	n/a
	Steady-Aeroelastic Cases (HIRENASD)	C <sub>L</sub> , C <sub>D</sub> , C <sub>M</sub> vs. N <sup>-2/3</sup>	n/a	<ul> <li>Mean C<sub>p</sub> vs. x/c</li> <li>Means of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub></li> <li>Vertical displacement vs. chord</li> <li>Twist angle vs. span</li> </ul>	n/a
	Forced Oscillation Cases (all configurations)	<ul> <li>Magnitude and Phase of CL, CD, CM vs. N<sup>-2/3</sup> at excitation frequency</li> </ul>	<ul> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> vs. ∆t at excitation frequency</li> </ul>	n/a	<ul> <li>Magnitude and Phase of C<sub>p</sub> vs. x/c at span stations corresponding to transducer locations</li> <li>Magnitude and Phase of C<sub>L</sub>, C<sub>D</sub>, C<sub>M</sub> at excitation frequency</li> <li>Time histories of C<sub>p</sub>'s at a selected span station for two upper- and two lower-surface transducer locations</li> </ul>



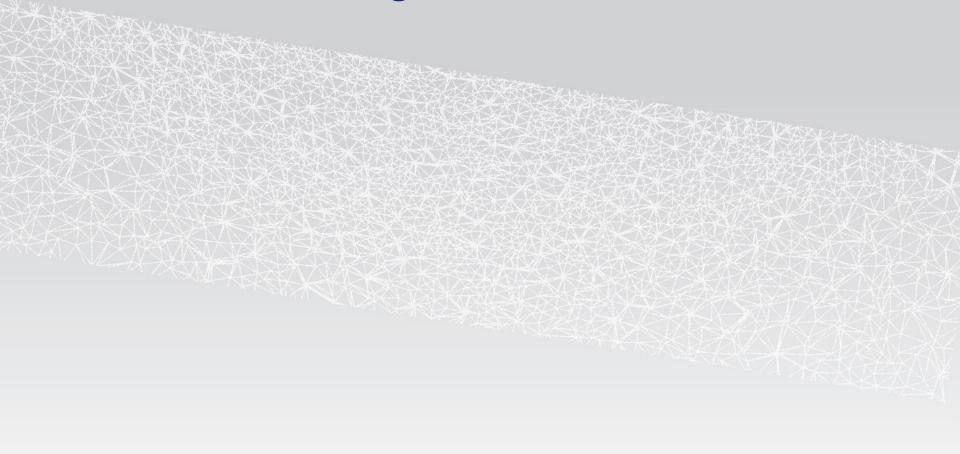


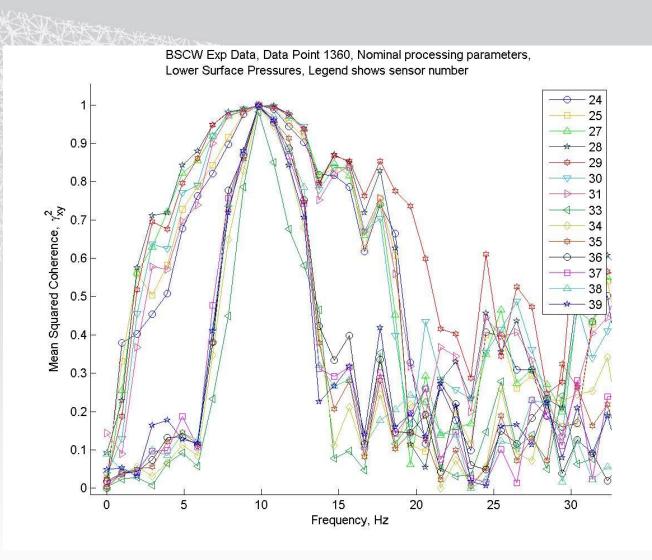
**Re-Variation:** Influence on lift and drag

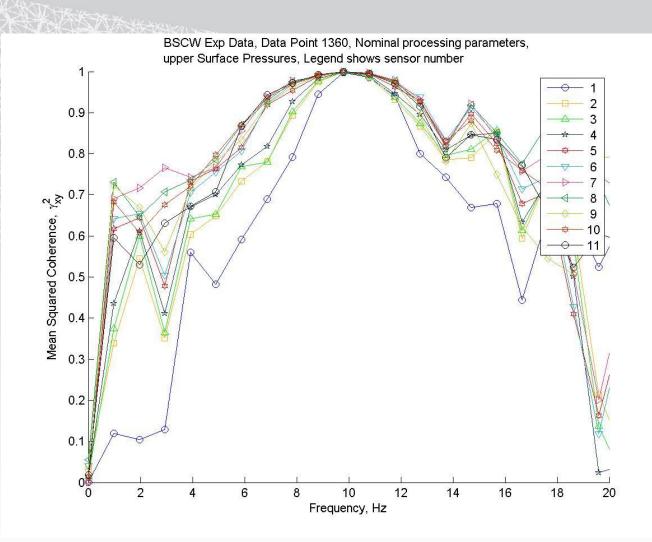


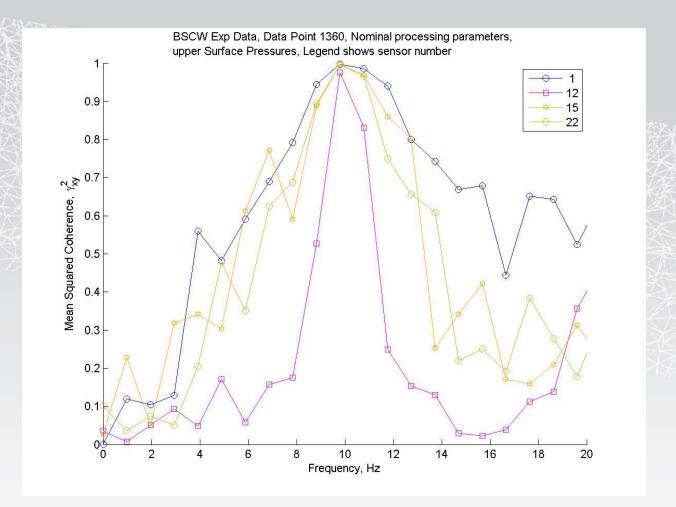


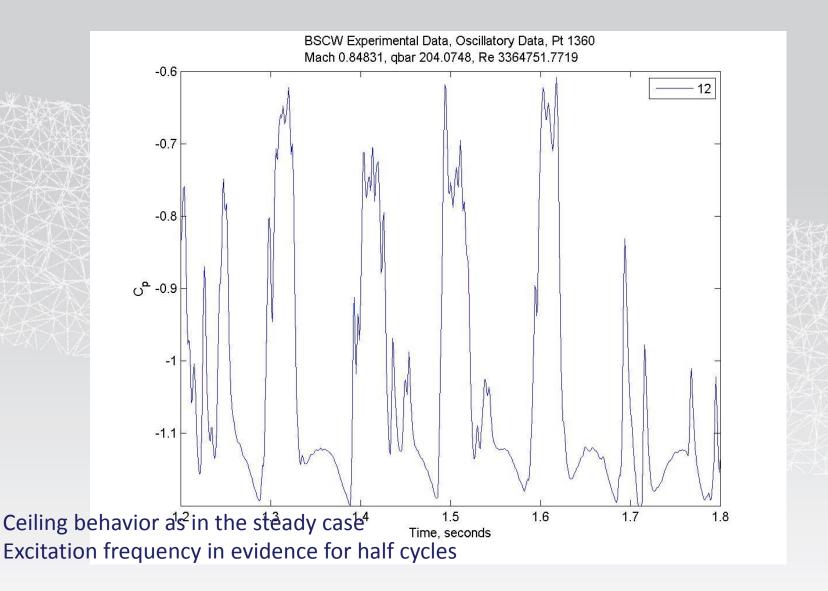
# Additional things about the BSCW data





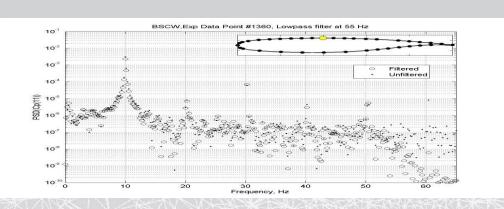






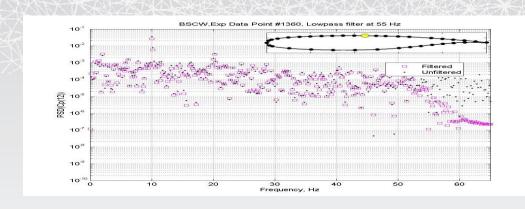
Excursion of shock across transducer (past transducer towards leading edge ) Occurs principally during the first ½ cycle of excitation shown

# Frequency content of the excursions?



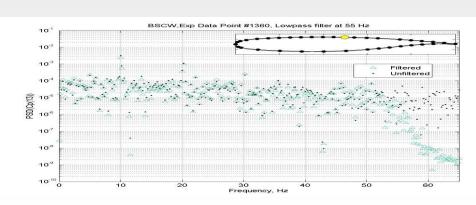
Nothing stands out when I look
At these to differentiate
Sensor 12 from the ones before and
After it...

Sensor #11

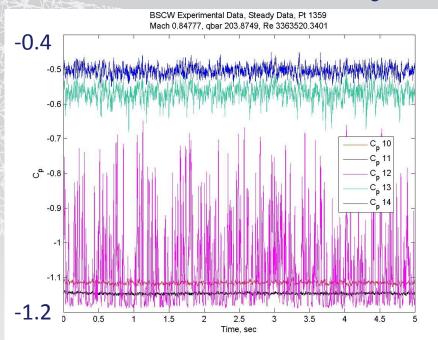


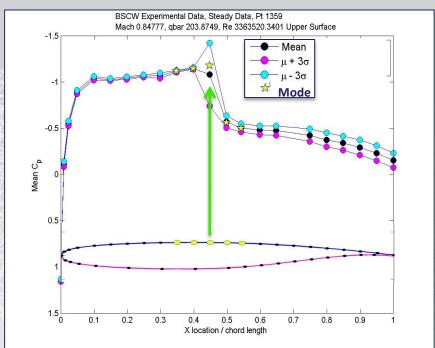
Sensor #12

Sensor #13



# BSCW Static Data: Steady Shock Location





### Location: just barely aft of upper surface transducer #12, x/c (12) = 0.448

(Note: x/c (13) = 0.498)

Upper surface pressure transducer 12: magenta data plot

Pressure floor at -1.17, i.e. it is bounded by -1.17

No well-defined, repeated ceiling value

Not sinusoidal

Expected pressure change across the shock:

large negative pressure ahead of the shock;

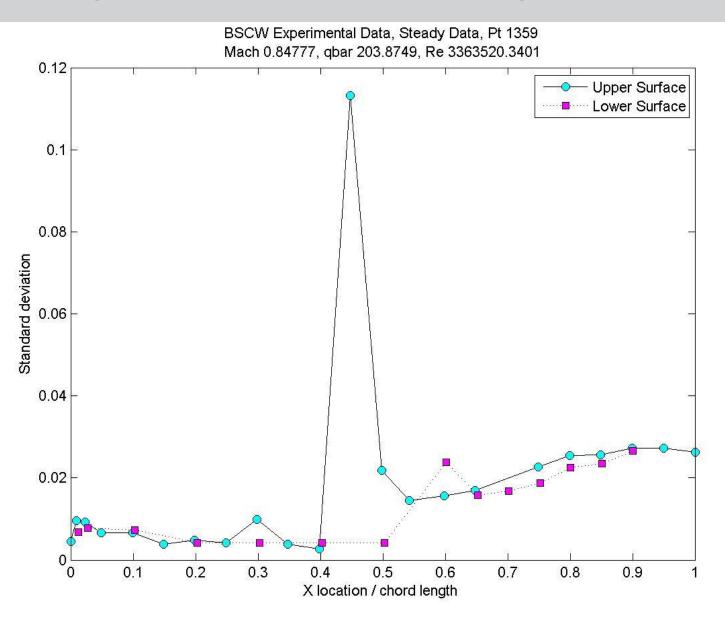
reduced negative pressure aft of the shock

Actual shock location is suspected to be just aft of this transducer location: the value oscillates to a higher pressure (aft of shock) as the shock moves Sensors towards leading edge (#10 and #11) have values near the minimum of #12

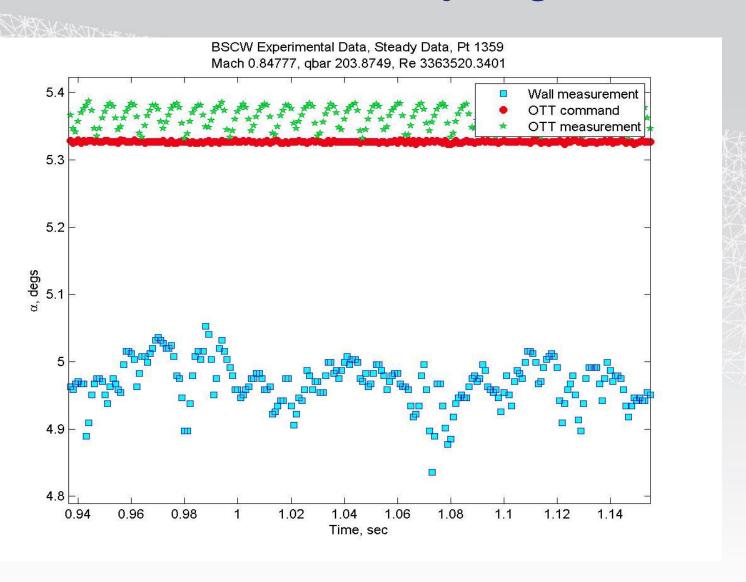
Sensors towards trailing edge (#13 and #14) have values beyond the maximum of #12

Simple interpretation: the sensor's preferred value reflects pressure ahead of shock, rather than aft of it.

## Standard Deviation of Static Data



# **BSCW Steady Angle**



# BSCW non-oscillated data

Splitter plate mode: ~15 Hz

Appears in the Wall Angle Measurement (WALLADT)

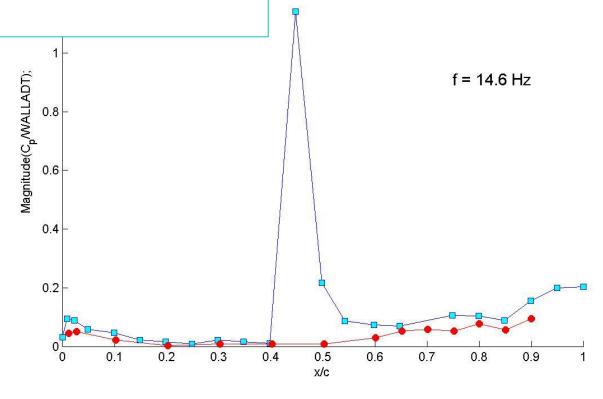
Appears in some of the wing sensors

Natural frequencies of BSCW:

24.1 Hz (spanwise 1<sup>st</sup> bending)

27.0 Hz (in-plane 1<sup>st</sup> bending)

79.9 Hz (1<sup>st</sup> torsion)



nental Data, Steady Data, Pt 1359 qbar 203.8749, Re 3363520.3401

Upper Surface

Lower Surface

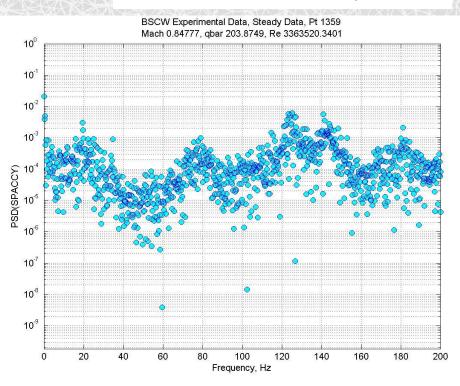
# **BSCW Static Data point**

Vertical splitter plate mode, 15 Hz

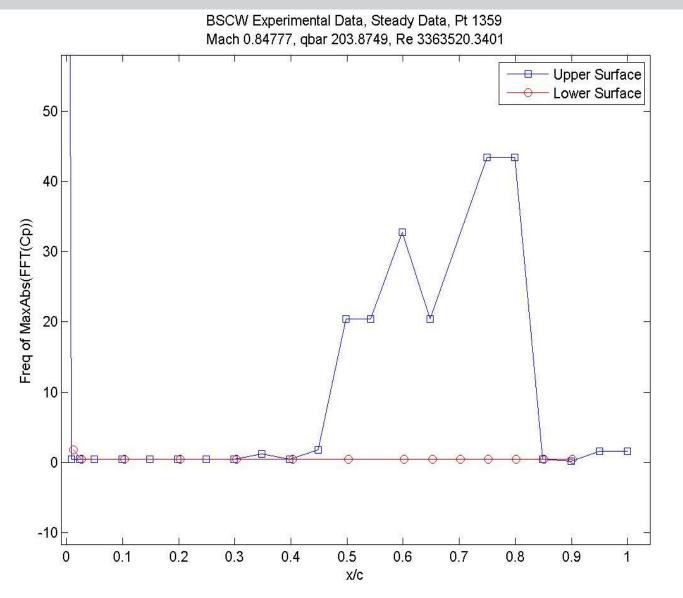
# Splitter Plate Accelerometer in the vertical "Z" direction, SPACCZ

# BSCW Experimental Data, Steady Data, Pt 1359 Mach 0.84777, qbar 203.8749, Re 3363520.3401 10<sup>-1</sup> 10<sup>-2</sup> 10<sup>-3</sup> 10<sup>-4</sup> 10<sup>-6</sup> 10<sup>-7</sup> 10<sup>-8</sup> 0 20 40 60 80 100 120 140 160 180 2 Frequency, Hz

# Splitter Plate Accelerometer in the wall-direction "Y", SPACCY



### **BSCW Non-oscillated data**



The different upper surface pressure transducers respond most strongly at different frequencies. ?to the different modes of the model?

# BSCW Static point, aeroelastic modes?

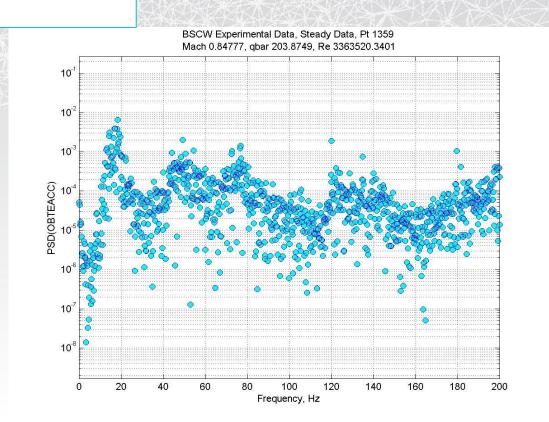
Splitter plate mode: ~15 Hz Appears in the Wall Angle Measurement (WALLADT) Appears in some of the wing sensors

Natural frequencies of BSCW:

24.1 Hz (spanwise 1<sup>st</sup> bending)

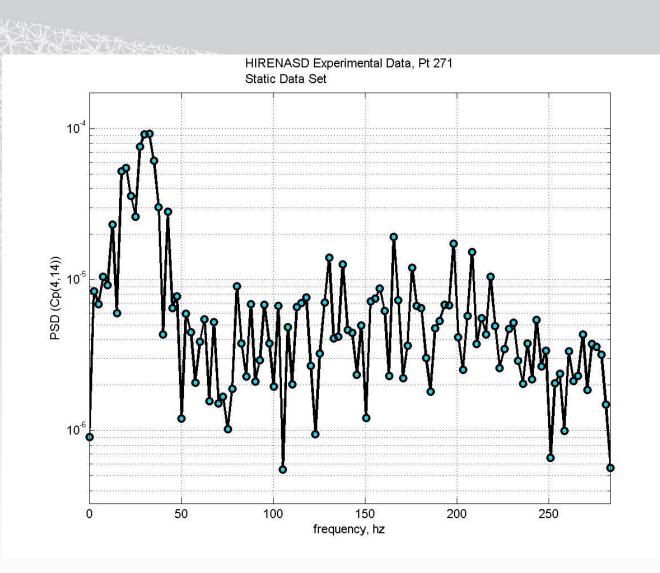
27.0 Hz (in-plane 1<sup>st</sup> bending)

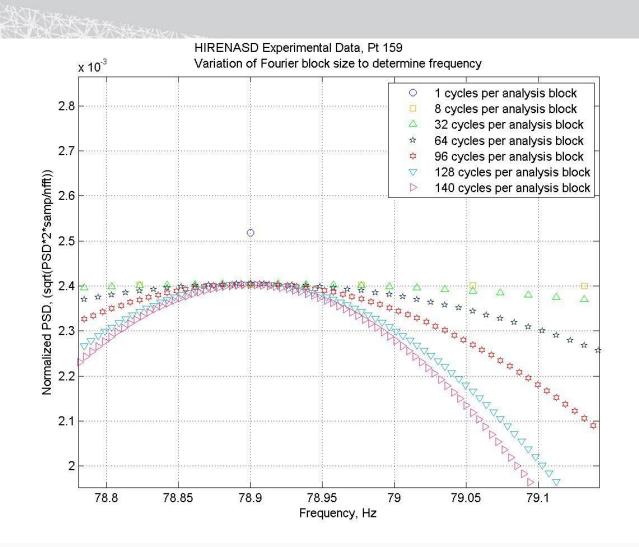
79.9 Hz (1<sup>st</sup> torsion)

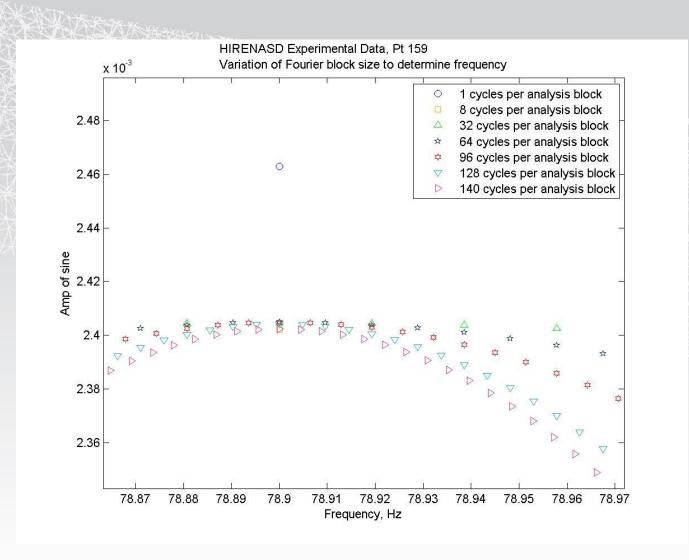


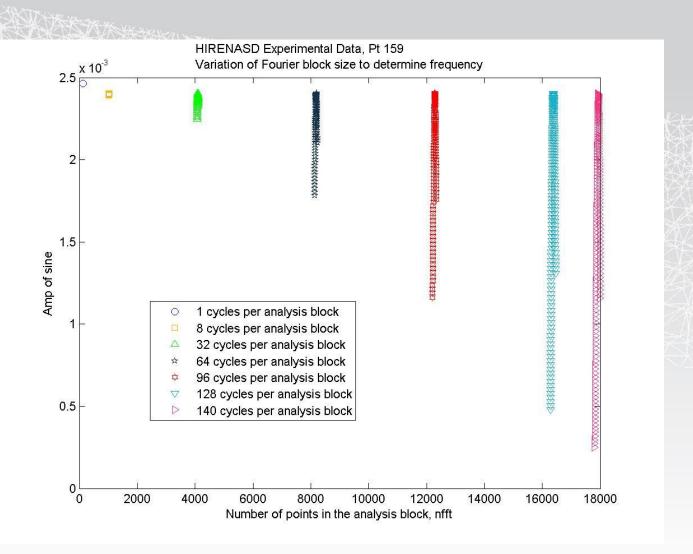
### **BSCW** notes

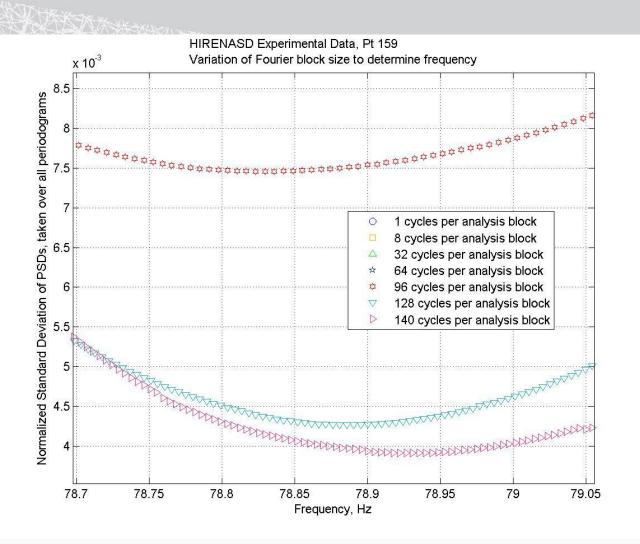
- Power spectral density functions computed for several sensors. Notice that the WALLADT shows the 15 Hz vertical (gravity-direction) splitter plate mode, but does not show the electronic noise peak at 60 Hz, which is present in the OTTADT. Notice that, as usual for the BSCW data examined to date, the presumed electronic noise spike at 120 Hz is the dominant peak.
- The 15 Hz splitter plate mode shows up strongly on the SPACCZ, which is the splitter plate accelerometer in the z direction. (tunnel floor to ceiling direction).
- SPACCY has peaks at 20 Hz and near 79 Hz. Are these the structural modes of the model? 1<sup>st</sup> spanwise bending mode, air off is at 24 Hz. 1<sup>st</sup> torsion, air off, is at 80 Hz.
- The PSDs of pressures aren't shown because nothing really jumps out of them to comment on.





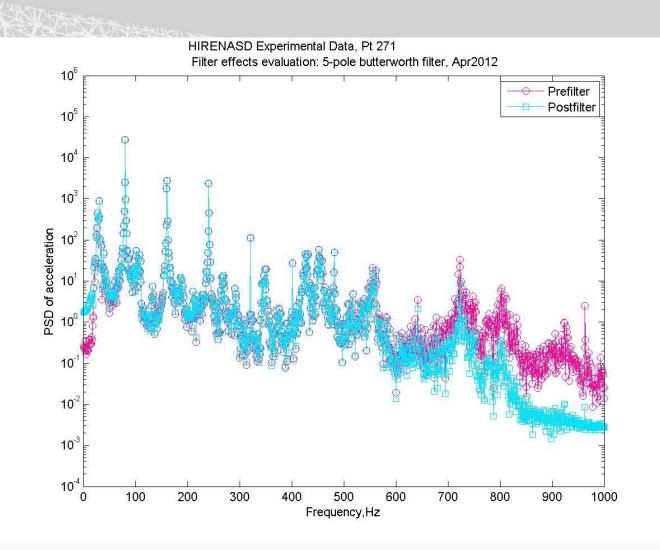




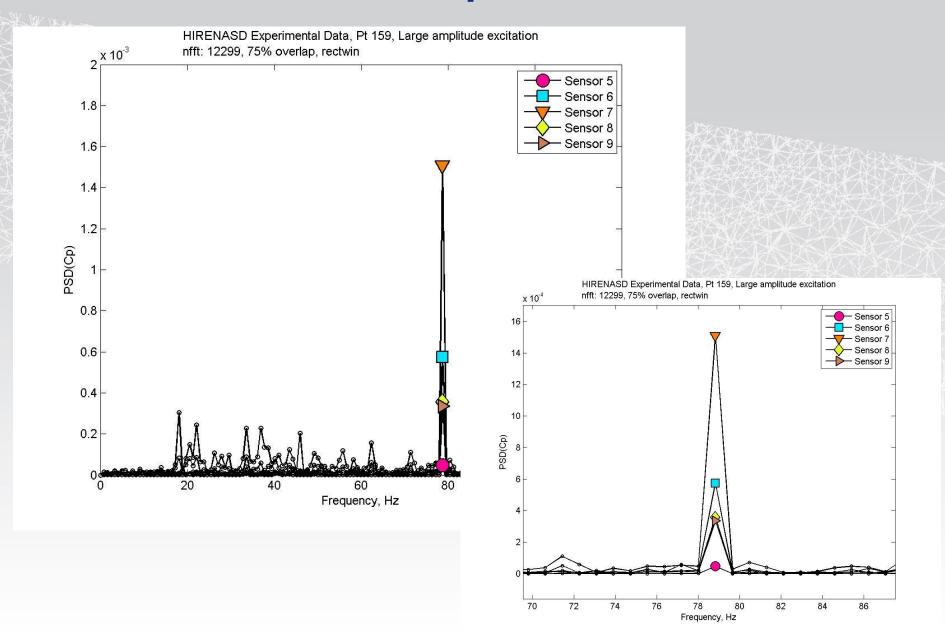


# HIRENASD experimental data uncertainty discussion notes

- In computing the transfer functions, the following have been identified as potential sources of variation, error or uncertainty.
- Off frequency (i.e. the excitation is not at exactly the natural or aeroelastic frequency): the variation effect will be highly dependent on damping. Frequency variation or error may be assessable using the stationary point data corresponding to the dynamic test conditions.
- Instrumentation accuracy: requires knowledge of the instrumentation specs and calibrations. This is the easiest source of error or variation to assess because we have instrumentation documentation and calibration documentation. However, in practice, repeat data points have had significantly more variation than could be accounted for through instrumentation accuracy. Jen's note: In the case of Active Aeroelastic Wing test conditions in the Transonic Dynamics-Tunnel, the test condition repeat point variation was more than an order of magnitude greater than that indicated by instrumentation accuracy.
  - Pressure transducers
  - Accelerometers
  - SPTs
- Tunnel measurement systems (static pressure, total pressure, temperature, etc)
- Mean angle of attack error: this can be due to flow redirection or instrumentation error or model alignment
- Model surface effects: If these effects are consistent during a time history, this isn't a cause of variation within the data, just a source of difference from the analytical results which we won't be
  able to capture or quantify unless we somehow have different model surfaces that allow us to assess this.
- Sidewall effects: as with model surface effects, this isn't a cause of variation within the experimental data set, just a source of difference with respect to the analytical results. Because we don't have an experimental variation on presence of the sidewall, it will be difficult to obtain an error due to the presence of the sidewalls. There was something in one of the AGARD reports regarding accounting for the sidewall, possibly associated with the supercritical wing?
- Tunnel disturbances: Can perhaps be evaluated by examination of two sets of data: one with excitation and one without. Examine the response levels at different frequencies.
- Test condition: variation of the test condition includes H,P,X,T, RPM or calculated parameters like Mach, dynamic pressure. Without experimental data where these were varied, we would have to rely on the analysis to propagate these parameters through and assess the impact on the analytical side.
- Excitation amplitude variation or error
- Data processing effects and assumptions:
  - Non-stationarity: can be assessed by analyzing different subsets of the data
  - Nonlinearity: Can be assessed by detailed examination of the time history and fourier domain data
  - Subsets of the data: see above
  - Method of reduction
  - Fourier processing parameters
    - Fourier block size
    - Overlap
    - Window
  - Data acquisition effects:
    - Voltage disturbances due to:
      - Cable lengths
      - Analog to digital converters



# PSD of pressure



# HIRENASD unsteady time history data: upper surface pressures

